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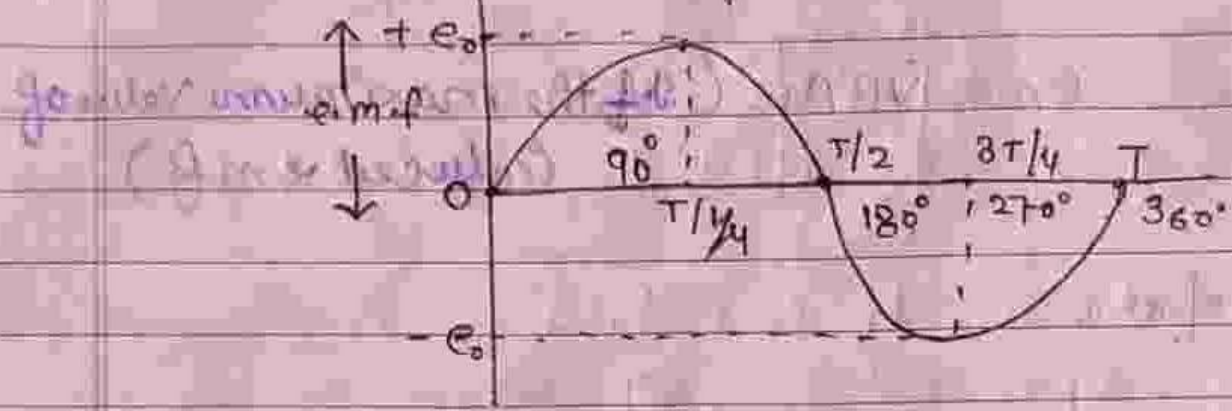


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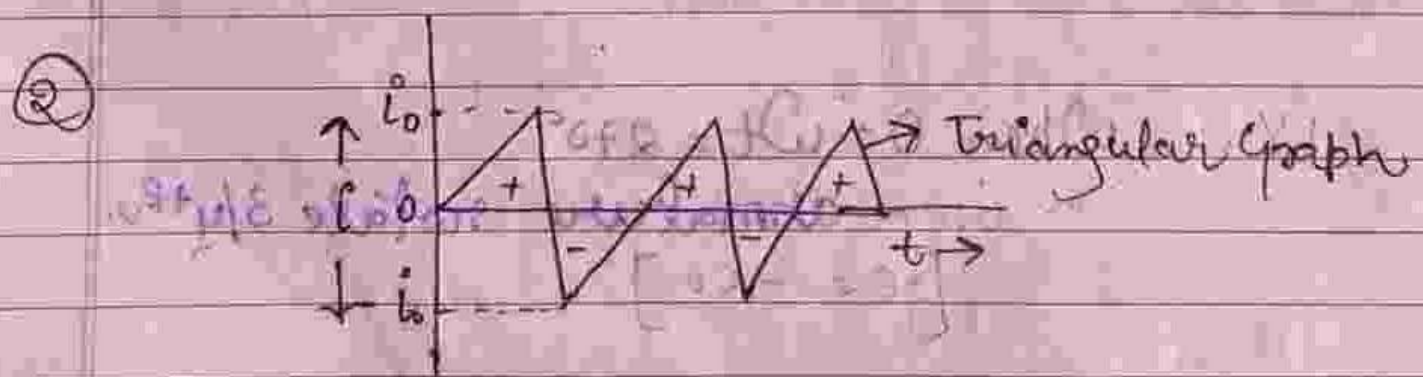
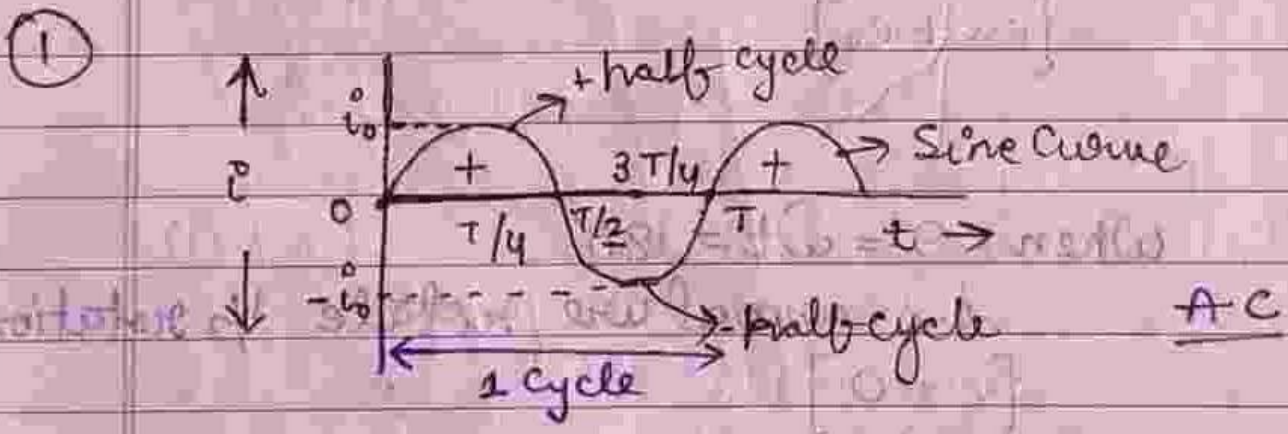


# ch-07 = Alternating Current

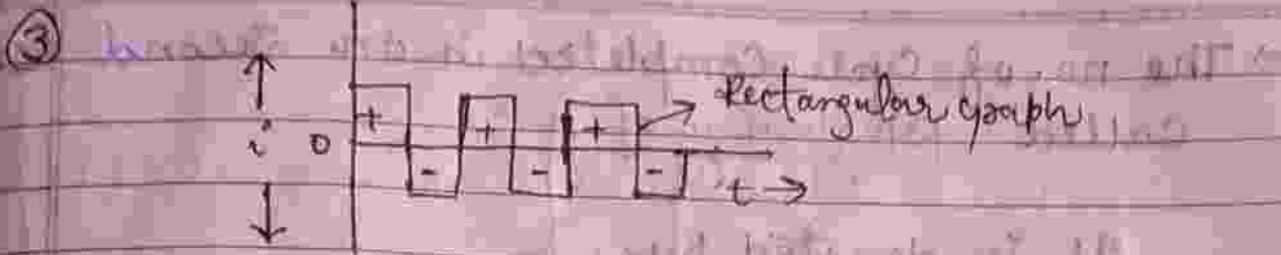


A current of constant amplitude which continuously varies in magnitude with time or change its direction periodically is called Alternating current.

Its eqn is -  $i = i_0 \sin \omega t$   
 where  $i_0 = \text{Amplitude of AC}$

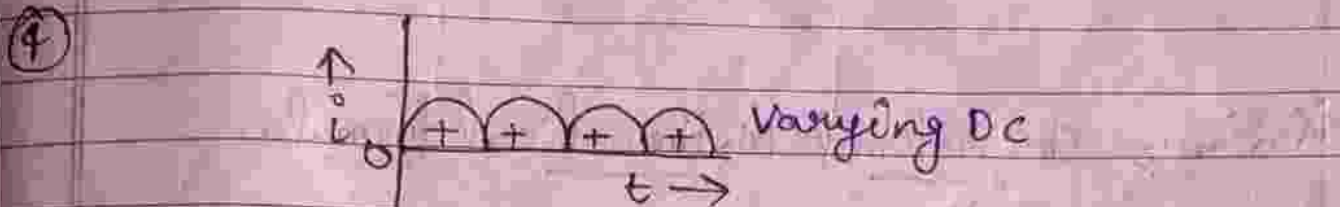


It is also AC

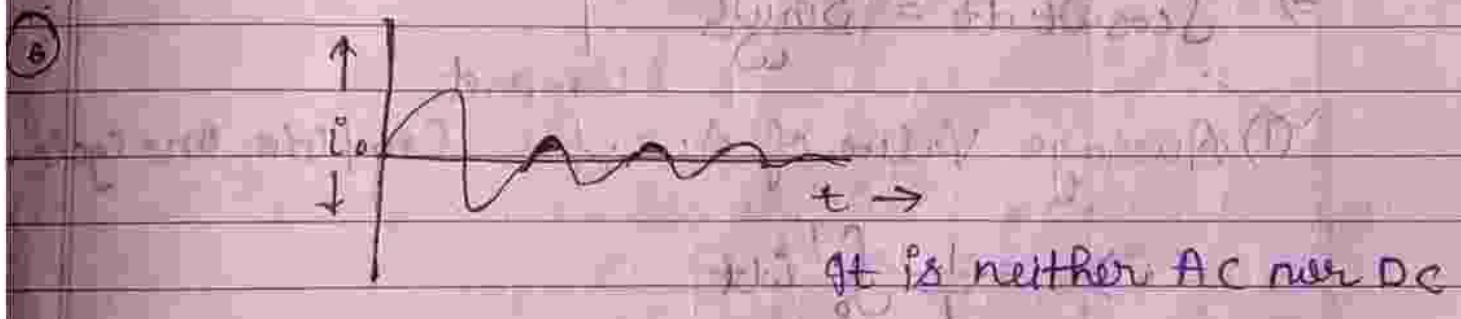
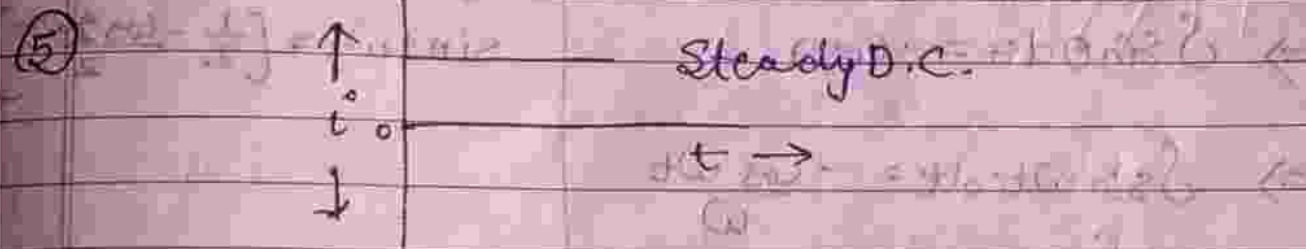


It is also A.C

(constant value) at time axis



It is neither A.C nor D.C



★  
① → The time taken to complete one cycle is called time period of A.C.

It is denoted by  $T$

$$T = \frac{2\pi}{\omega}$$

Note - The average value of any  $x$  is denoted by  $\langle x \rangle$  or  $\bar{x}$  or  $x_{av}$

→ The no. of cycle completed in one second is called Frequency of AC

It is denoted by  $f$

its unit is Hz (cycle/sec)

★ Some Important Mathematical Formula

$$\Rightarrow \int \cos \theta d\theta = \sin \theta$$

$$\Rightarrow \int \sin \theta d\theta = -\cos \theta$$

$$\Rightarrow \int \sin \omega t dt = -\frac{\cos \omega t}{\omega}$$

$$\Rightarrow \int \cos \omega t dt = \frac{\sin \omega t}{\omega}$$

$$\Rightarrow \cos^2 \omega t = 1 - 2\sin^2 \omega t$$

$$2\sin^2 \omega t = 1 - \cos 2\omega t$$

$$\sin^2 \omega t = \left[ \frac{1 - \cos 2\omega t}{2} \right]$$

constant

① Average Value of AC: for complete one cycle.

$$\langle i \rangle = \frac{1}{T} \int_0^T i dt$$

$$= \frac{1}{T} \int_0^T i_0 \sin \omega t dt$$

$$= \frac{i_0}{T} \int_0^T \sin \omega t dt$$

$$= \frac{i_0}{T} \left[ -\frac{\cos \omega t}{\omega} \right]_0^T \quad \because \omega = \frac{2\pi}{T}$$

$$= \frac{i_0}{T\omega} [-\cos \omega T + \cos 0]$$

$$\sin 2\pi, 6\pi, 8\pi, 10\pi \text{ etc} = 0$$

even  $\sin \pi$

$$= \frac{i_0}{T\omega} \left[ -\cos \frac{2\pi}{T} \times T + \cos 0 \right]$$

$$\langle i \rangle = \frac{i_0}{T\omega} \left[ -\cos 2\pi + \cos 0 \right]$$

$$= \frac{i_0}{T\omega} \left[ -1 + 1 \right]$$

$$\star \left[ \langle i \rangle = 0 \right]$$

② Average value of A.C <sup>current</sup> after half cycle

$$\langle i \rangle = \frac{1}{(T/2)} \int_0^{T/2} i dt$$

$$= \frac{2}{T} \int_0^{T/2} i_0 \sin \omega t dt$$

$$= \frac{2i_0}{T} \left[ -\frac{\cos \omega t}{\omega} \right]_0^{T/2}$$

$$= \frac{2i_0}{T\omega} \left[ +\cos \omega \frac{T}{2} + \cos 0 \right]$$

$$= \frac{2i_0}{T\omega} \left[ -\cos \frac{2\pi}{T} \times \frac{T}{2} + \cos 0 \right]$$

$$\langle i \rangle = \frac{2i_0}{\cancel{2\pi} \times \cancel{\omega}} \left[ -\cos 2\pi + 1 \right]$$

$$\langle i \rangle = \frac{i_0}{\pi} \left[ +1 + 1 \right]$$

$$\left[ \langle i \rangle = +\frac{2i_0}{\pi} \right] \rightarrow \left[ \langle i \rangle = +0.637 i_0 \right]$$

current

The average value of A.C. for -ve half cycle

$$\left[ \langle i \rangle = -\frac{2i_0}{\pi} \right] \rightarrow \left[ \langle i \rangle = -0.637 i_0 \right]$$

Similarly the average value of A.C. voltage for one + half cycle.

$$\langle v \rangle = \frac{+2v_0}{\pi}$$

For another - half cycle

$$\langle v \rangle = -\frac{2v_0}{\pi}$$

★ Root mean Square Value of AC

$$[i_{rms}]$$

The square root of average value of square of AC for one cycle is called rms value of alternating current.

$$i_{rms} = \sqrt{\overline{i^2}} \text{ for complete one cycle}$$

$$\overline{i^2} = \frac{1}{T} \int_0^T i^2 dt$$

$$\overline{i^2} = \frac{1}{T} \int_0^T i_0^2 \sin^2 \omega t dt$$

$$V_{rms} = 220V.$$

$$220 = \frac{V_0}{\sqrt{2}}$$

$$V_0 = 220\sqrt{2} = 311 \text{ volt}$$

$$\overline{i^2} = \frac{i_0^2}{T} \int_0^T \left[ \frac{1}{2} - \frac{\cos 2\omega t}{2} \right] dt$$

$$\overline{i^2} = \frac{i_0^2}{T} \left[ \int_0^T \frac{1}{2} dt - \frac{1}{2} \int_0^T \cos 2\omega t dt \right]$$

$$\overline{i^2} = \frac{i_0^2}{T} \left[ \frac{T}{2} - \frac{1}{2} \left[ \frac{\sin 2\omega t}{2\omega} \right]_0^T \right]$$

$$\overline{i^2} = \frac{i_0^2}{T} \left\{ \frac{T}{2} - \frac{1}{2} \left[ \frac{\sin 2\omega t}{2\omega} - \sin 0 \right] \right\}$$

$$\overline{i^2} = \frac{i_0^2}{T} \left\{ \frac{T}{2} - \frac{1}{4\omega} \left[ \sin 2 \times \frac{2\pi}{T} \times T - 0 \right] \right\}$$

$$\overline{i^2} = i_0^2 \times \frac{T}{2} \quad \because \sin 4\pi = 0$$

$$\overline{i^2} = \frac{i_0^2}{2}$$

Therefore

$$i_{rms} = \sqrt{\frac{i_0^2}{2}}$$

$$\left[ i_{rms} = \frac{i_0}{\sqrt{2}} \right]$$

Similarly

$$\left[ V_{rms} = \frac{V_0}{\sqrt{2}} \right]$$

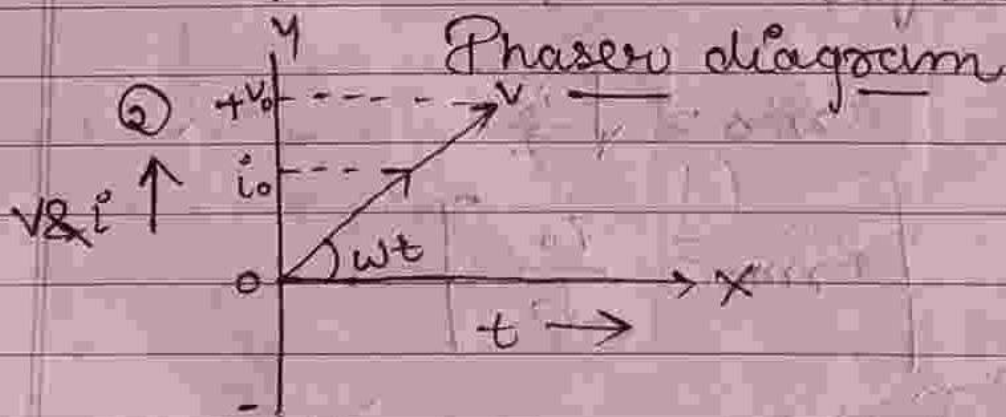
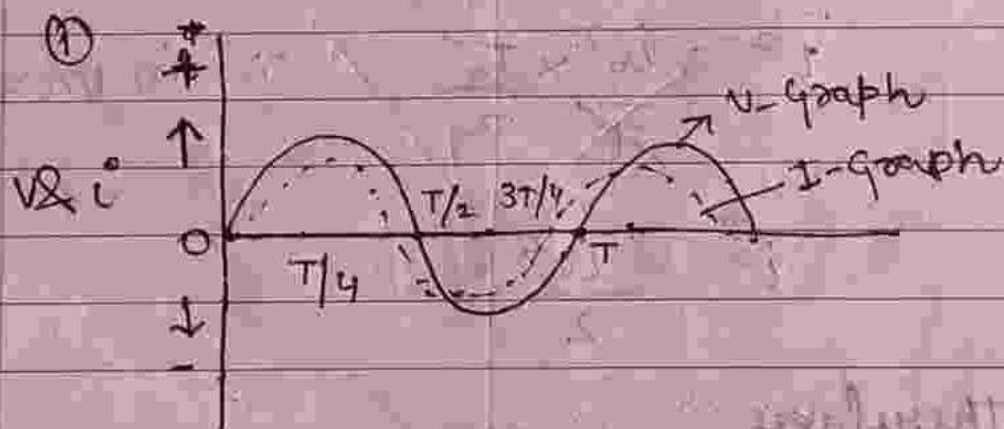


# Phase difference b/w AC (Current) and AC Voltage.

① → When  $V$  and  $i$  both are in same phase.

→ To show the phase relationship b/w voltage and current in an AC circuit we use the phaser diagram.

“The phaser diagram is the rotating vector representing A.C and voltage.”



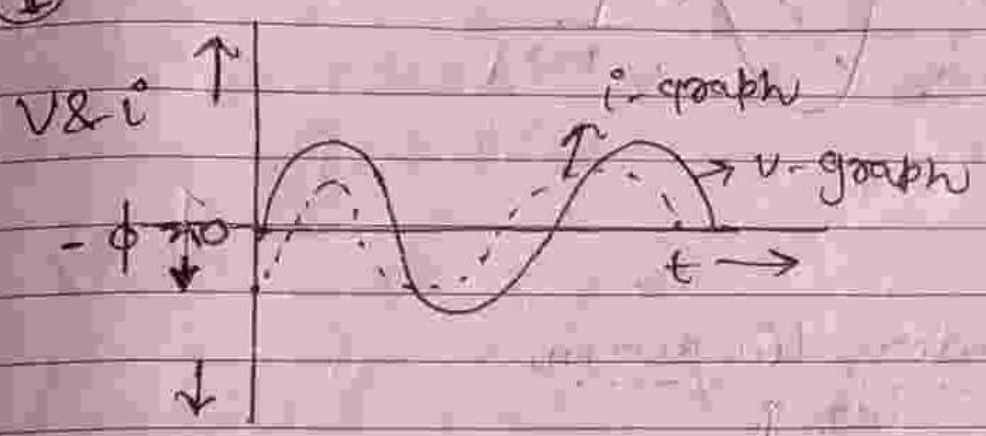
③

$$\begin{bmatrix} V = V_0 \sin \omega t \\ i = i_0 \sin \omega t \end{bmatrix}$$

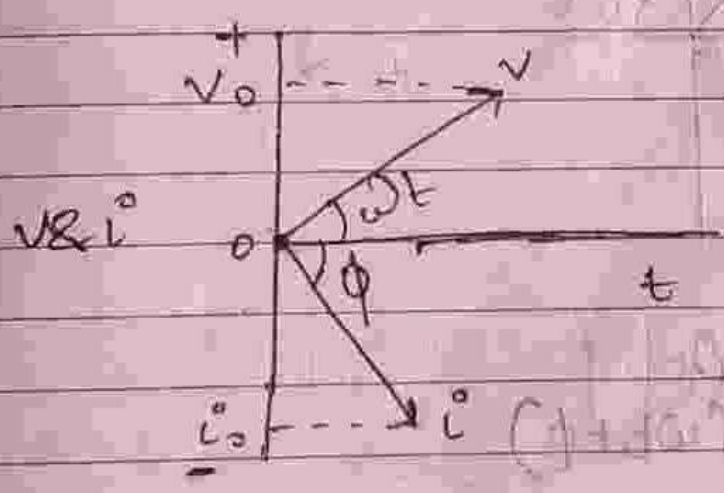
ii) When AC voltage  $V$  is leading by  $\phi$  phase with  $i$  or

$i$  is lagging by  $\phi$  phase with  $V$

①



② Phasor diagram

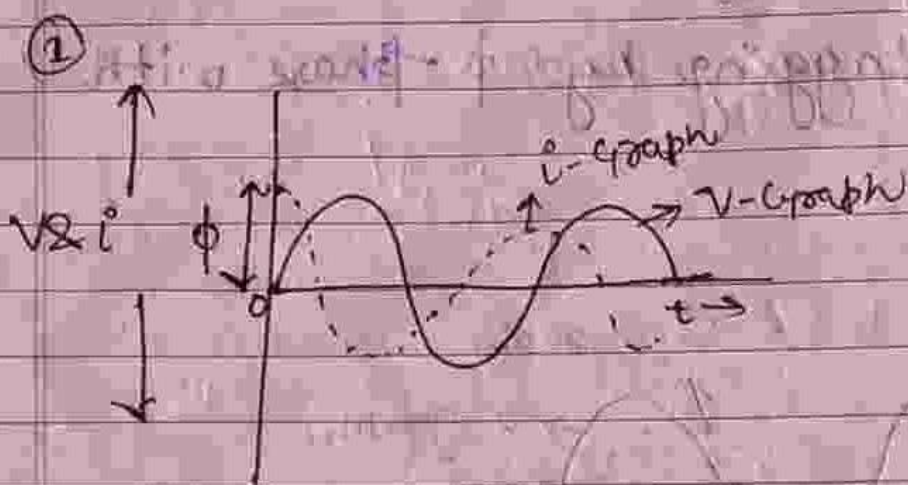


③ 
$$\left[ \begin{array}{l} V = V_0 \sin \omega t \\ i = i_0 \sin (\omega t - \phi) \end{array} \right]$$

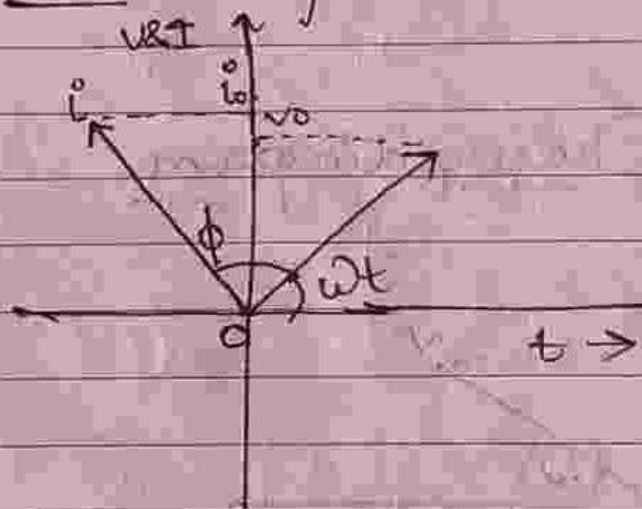
or

$$\left[ \begin{array}{l} V = V_0 \sin (\omega t + \phi) \\ i = i_0 \sin \omega t \end{array} \right]$$

iii) When Voltage lags Current by phase  $\phi$  or the Current leads Voltage by phase  $\phi$



② Phaser diagram



③

$$V = V_0 \sin \omega t$$

$$i = i_0 \sin(\omega t + \phi)$$

OR

$$V = V_0 \sin \omega t$$

$$V = V_0 \sin(\omega t - \phi)$$

NOTES →  AC source

 cell

## Different types of AC circuit

① When there is only a resistor. R-cot

$$V = V_0 \sin \omega t \quad \text{--- (1)}$$



The voltage across R

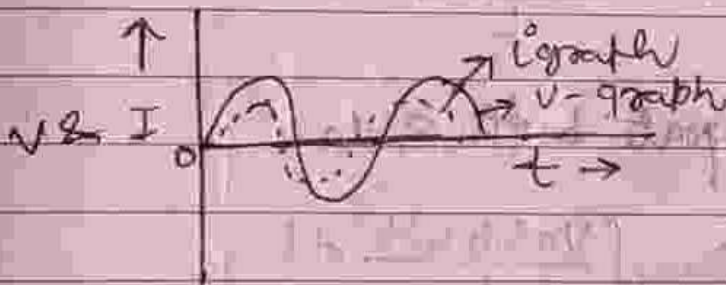
$$V = iR$$

$$i = \frac{V}{R} = \frac{V_0 \sin \omega t}{R}$$

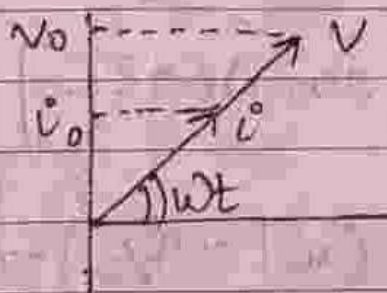
$$i = i_0 \sin \omega t \quad \text{--- (2)}$$

$$\therefore \frac{V_0}{R} = i_0$$

In R-cot the V & i will be in same phase.

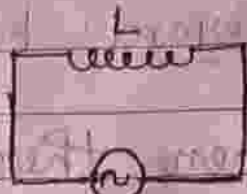


## Phasor diagram



② L-cot (Inductance)

$$V = V_0 \sin \omega t \quad - (1)$$



The induced e.m.f across L

$$V = V_0 \sin \omega t$$

$$e = -L \frac{di^{\circ}}{dt}$$

To maintain current in ct the applied voltage will be.

$$V = -e$$

$$V = L \frac{di^{\circ}}{dt}$$

$$di^{\circ} = \frac{V}{L} dt$$

$$di^{\circ} = \frac{V_0 \sin \omega t}{L} dt$$

Integrate both side

$$\int di^{\circ} = \int \frac{V_0 \sin \omega t}{L} dt$$

$$i^{\circ} = \frac{V_0}{L} \left[ -\frac{\cos \omega t}{\omega} \right]$$

$$i^{\circ} = \frac{V_0}{\omega L} \left[ \sin \omega t - \frac{\pi}{2} \right]$$

$$i = i_0 \sin (\omega t - \pi/2) \quad - (2)$$

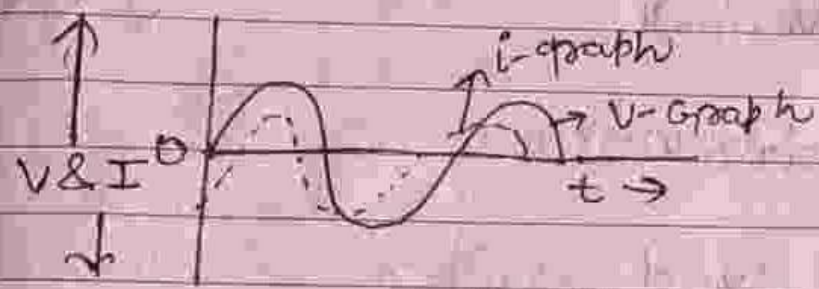
where  $i_0 = \frac{V_0}{\omega L}$

NOTES →  $R$  → Resistance  
 $X_L$  → Inductive Reactance  
 $X_C$  → Capacitive Reactance  
 $Z$  → Impedance Reactance

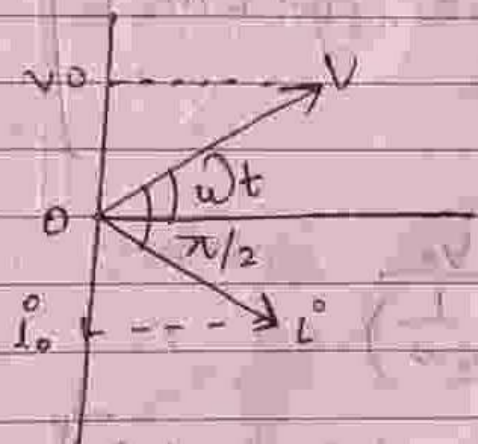
Unit  
 $\Omega$

⇒ In L-Ckt the voltage leading with current by phase  $\pi/2$

or the current lagging with voltage by phase  $\pi/2$



Phasor Graph



$$\frac{V_0}{I_0} = \omega L$$

$\frac{V_0}{I_0} =$  Resistance of ckt

$\frac{V_0}{I_0} = X_L =$  Inductive Reactance

$$[X_L = \omega L]$$

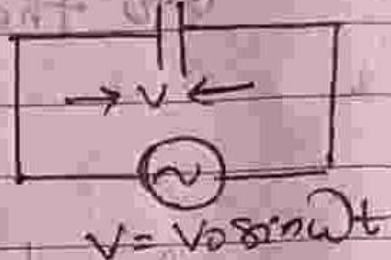
The SI unit of Inductive Reactance -  $(\Omega)$  ohm

② RC-circuit

When there is only capacitor in AC circuit.

$$q = CV$$

$$q = C V_0 \sin \omega t$$



differentiate w.r.t to t

$$\frac{dq}{dt} = C V_0 \frac{d}{dt} \sin \omega t$$

$$i = C V_0 \times (\cos \omega t) \times \omega$$

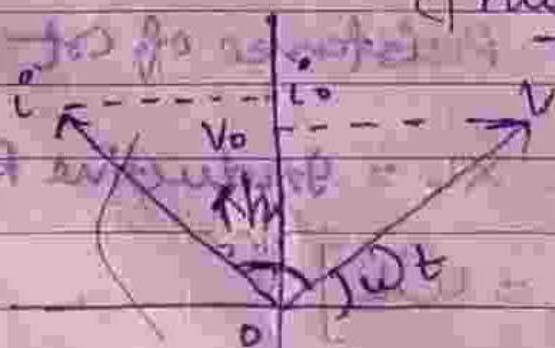
$$i = C \omega V_0 \cos \omega t$$

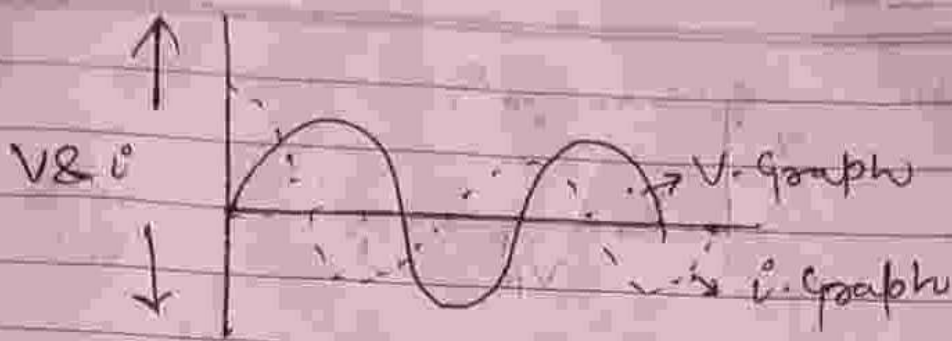
$$\left[ i = \frac{V_0}{\left(\frac{1}{C\omega}\right)} \sin(\omega t + \pi/2) \right]$$

$$i = \frac{V_0}{\left(\frac{1}{C\omega}\right)} = i_0$$

$$\therefore \left[ i = i_0 \sin(\omega t + \pi/2) \right]$$

Phasor diagram





$$\therefore i_0 = \frac{V_0}{\left(\frac{1}{c\omega}\right)}$$

$$\left(\frac{V_0}{i_0}\right) = \frac{1}{c\omega}$$

$$\left[ X_c = \frac{1}{\omega c} \right]$$

Capacitive  
Reactance

$$\therefore \omega = 2\pi f$$

$$\left[ X_c = \frac{1}{2\pi f c} \right]$$

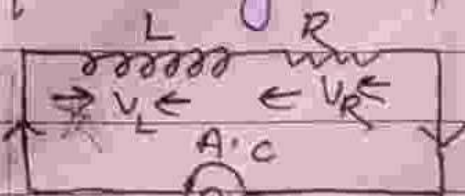
★  
" Therefore in C-ckt current lead voltage by phase  $\pi/2$  "

or, voltage lags current by phase  $\pi/2$

(5) L-R Circuit

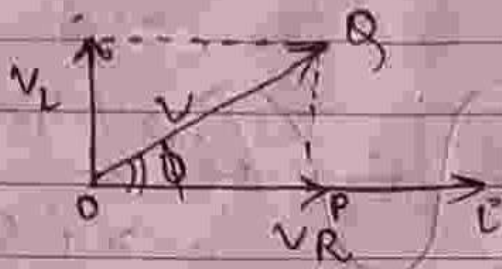
Let the phase difference b/w voltage and current is  $\phi$ .

$$\left(\frac{V_0}{i_0}\right) \cos \phi = \dots$$



$$V = V_0 \sin \omega t$$





Resultant potential

$$V^2 = V_R^2 + V_L^2$$

$$V = \sqrt{V_R^2 + V_L^2}$$

$$V = \sqrt{i^2 R^2 + i^2 X_L^2} \quad \because V_R = iR \quad V_L = iX_L$$

$$\left[ \frac{V}{i} \right] = \left[ \sqrt{R^2 + X_L^2} \right]$$

$\frac{V}{i}$  is called impedance of the circuit

it is denoted by Z

$$\therefore Z = \sqrt{R^2 + X_L^2} \quad \because X_L = \omega L$$

$$Z = \sqrt{R^2 + (\omega L)^2}$$

The unit of Z is ohms (Z)

Let the phase diff. b/w i & V is φ.

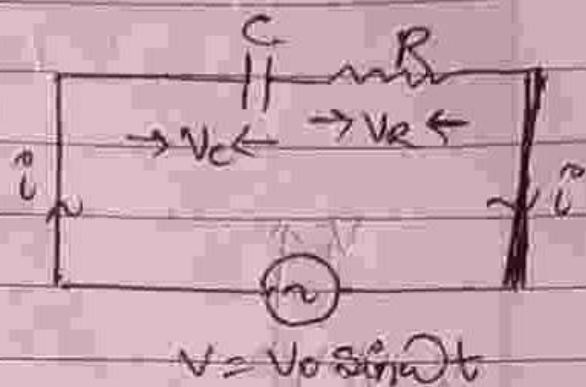
$$\sin \phi = \frac{PQ}{OQ} = \frac{V_L}{V} = \frac{iX_L}{iR} = \frac{\omega L}{R}$$

$$\star \left[ \phi = \tan^{-1} \left( \frac{\omega L}{R} \right) \right]$$

## ✓ C-R Circuit

Resultant Voltage

$$V = \sqrt{V_R^2 + V_C^2}$$

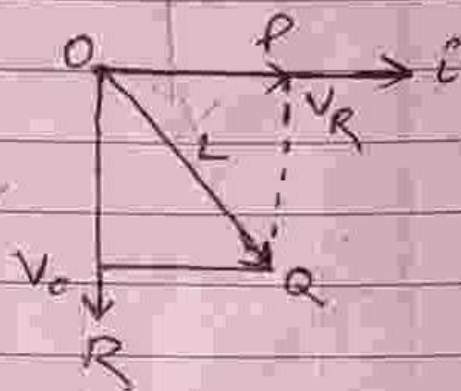


$$\begin{aligned} \therefore V_R &= i R \\ V_C &= i \times X_C \\ &= i \times \frac{1}{\omega C} \end{aligned}$$

$$V = \sqrt{i^2 R^2 + i^2 \left(\frac{1}{\omega C}\right)^2}$$

$$V = i \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$$\frac{V}{i} = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$



$\frac{V}{i}$  is impedance of circuit

$$\left[ Z = \sqrt{R^2 + \frac{1}{(\omega C)^2}} \right]$$

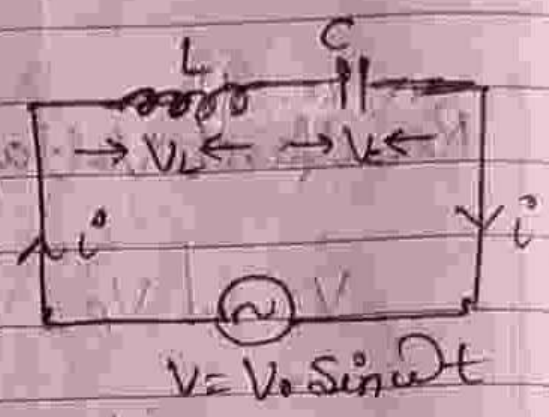
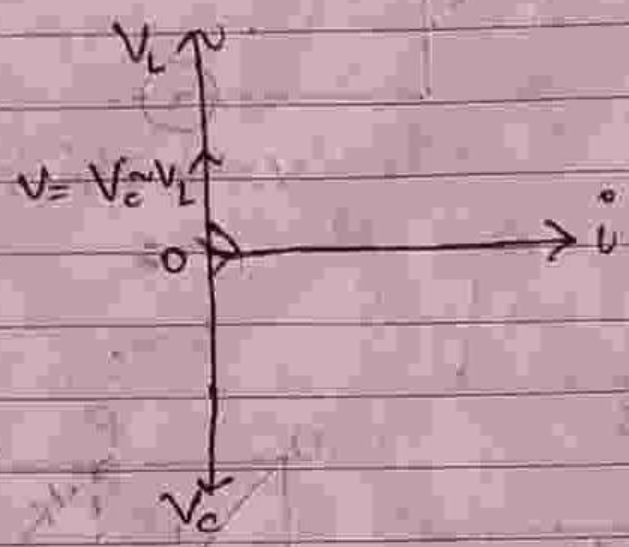
Let the phase diff. b/w  $i$  &  $V$  is  $\phi$

$$\tan \phi = \frac{PQ}{OP} = \frac{V_C}{V_R} = \frac{i \times X_C}{i R} = \frac{1}{\omega C R}$$

$$\tan \phi = \frac{1}{\omega C R}$$

$$\star \left[ \phi = \tan^{-1} \left( \frac{1}{\omega C R} \right) \right]$$

# L-C Circ



$$V = V_L \sim V_C$$

$$V_L = i \times X_L$$

$$V_C = i \times X_C$$

$$V = i \times X_L \sim i \times X_C$$

$$\frac{V}{i} = X_L \sim X_C$$

$\frac{V}{i}$  is the impedance of circ

$$[Z = X_L \sim X_C]$$

The phase difference b/w Res of Voltage and current will be  $\pi/2$

## Electrical Resonance

When,  $X_L = X_C$   
then  $[Z = 0]$

In this condition the amplitude of current will be maximum.

At electrical Resonance

$$X_L = X_C$$

$$\omega L = \frac{1}{\omega C}$$

$$2\pi fL = \frac{1}{2\pi fC}$$

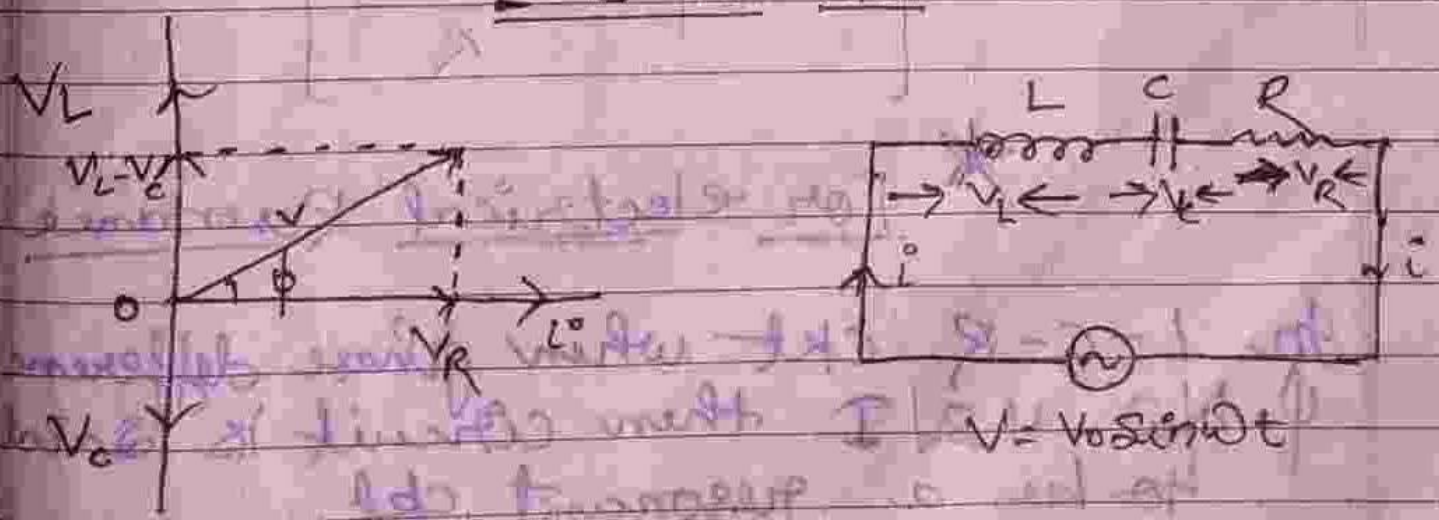
$$f^2 = \frac{1}{4\pi^2 LC}$$

$$f = \frac{1}{\sqrt{4\pi^2 LC}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{1}{LC}}$$

f is called Resonance frequency

L-C-R Ckt



## Resultant Potential of ckt

$$V^2 = V_R^2 + (V_L - V_C)^2$$

$$V^2 = i^2 R^2 + (iX_L - iX_C)^2$$

$$\frac{V^2}{i^2} = R^2 + (X_L - X_C)^2$$

$$\frac{V}{i} = \sqrt{R^2 + (X_L - X_C)^2}$$

$\frac{V}{i}$  is the impedance of ckt

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

$$\left[ Z = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2} \right]$$

Let the phase difference b/w voltage and current is  $\phi$

tan of angle  $\phi = \frac{V_L - V_C}{V_R} = \frac{iX_L - iX_C}{iR}$

$$\left[ \tan \phi = \frac{\omega L - \frac{1}{\omega C}}{R} \right]$$



For electrical Resonance

In L-C-R ckt when phase difference  $\phi$  b/w  $V$  &  $I$  then circuit is said to be a resonant ckt.

This is possible -

$$\omega L = \frac{1}{\omega C}$$

from

$$Z = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$$

$$[Z = R]$$

In L-C-R ckt there will be electrical resonance when the impedance of the circuit will be equal to the resistance.

$$\omega L = \frac{1}{\omega C}$$

$$2\pi f L = \frac{1}{2\pi f C}$$

$$f^2 = \frac{1}{4\pi^2 LC}$$

$$\left[ f = \frac{1}{2\pi} \sqrt{\frac{1}{LC}} \right]$$

This frequency is called Resonance frequency

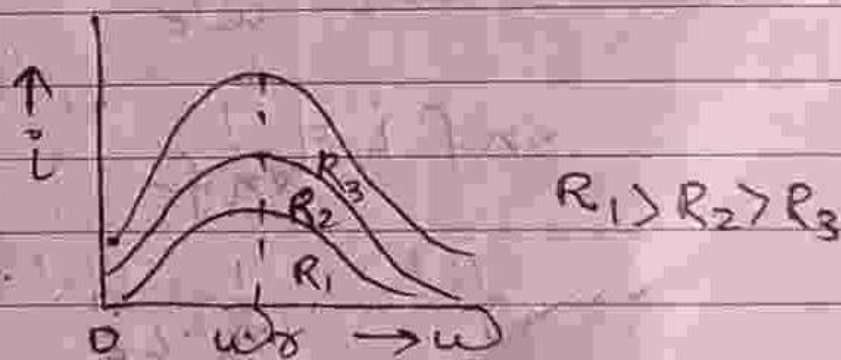
## The Sharpness of Resonance

- depend upon the quality factor of circuit

- The quality factor is the ratio of voltage develop across  $L$  or  $C$  & Voltage across resistance.

- It is denoted by  $Q$

$$Q = \frac{\text{Voltage across } L \text{ or } C}{\text{Voltage across } R}$$



## Average power associated in AC circuit

$$P = \frac{dW}{dt} \quad \text{--- (1)}$$

$$P = V_i^2 \quad \text{--- (2)}$$

$$dt \Rightarrow \frac{dW}{dt} = v i$$

$$dW = v i dt$$

Let the phase diff. b/w Voltage & current is  $\phi$

$$dW = (V_0 \sin \omega t) (i_0 \sin(\omega t + \phi)) dt$$

Average work done in one cycle.

$$W = \int_0^T dW = \int_0^T V_0 i_0 \sin \omega t \sin(\omega t + \phi) dt$$

$$W = V_0 i_0 \int_0^T \sin \omega t [\sin \omega t \cos \phi + \cos \omega t \sin \phi] dt$$

$$W = V_0 i_0 \int_0^T (\sin^2 \omega t \cos \phi + \sin \omega t \cos \omega t \sin \phi) dt$$

$$W = \frac{V_0 i_0}{2} \int_0^T [2 \sin^2 \omega t \cos \phi + 2 \sin \omega t \cos \omega t \sin \phi] dt$$

$$\begin{aligned} & \because 2 \sin \omega t \cos \omega t \\ & = \sin 2\omega t \end{aligned}$$

$$W = \frac{V_0 i_0}{2} \left[ \int_0^T 2 \sin^2 \omega t \cos \phi dt + \int_0^T \sin 2\omega t \sin \phi dt \right]$$

$$W = \frac{V_0 i_0}{2} \left[ \int_0^T (1 + \cos 2\omega t) \cos \phi dt + \int_0^T \sin 2\omega t \sin \phi dt \right]$$

$$W = \frac{V_0 i_0}{2} \left[ \int_0^T \cos \phi dt + \cos \phi \int_0^T \cos 2\omega t dt + \sin \phi \int_0^T \sin 2\omega t dt \right]$$



$$\therefore \cos 2\omega t = 2 \sin^2 \omega t - 1$$

$$2 \sin^2 \omega t = \cos \omega t + 1$$

$$W = \frac{V_0 I_0}{2} \times \cos \phi [t]_0^T \quad \therefore \int_0^T \cos 2\omega t dt = 0$$

$$\Rightarrow W = \frac{V_0 I_0}{2} \times \cos \phi \times T \quad \int_0^T \sin 2\omega t dt = 0$$

$$\bar{P} = \frac{W}{T} \Rightarrow \bar{P} = \frac{V_0 I_0}{2} \cos \phi \times T \div T$$

$$\left[ \bar{P} = \frac{V_0 I_0}{2} \times \cos \phi \right]$$

$$\bar{P} = \frac{V_0}{\sqrt{2}} \times \frac{I_0}{\sqrt{2}} \cos \phi$$

$$\left[ P = V_{rms} \times I_{rms} \cos \phi \right]$$

↓  
Power factor

### Average Power

$$\cos \phi = \text{Power factor}$$

R-ckt

$$\text{for R-ckt } \phi = 0$$

$$P_{av} = V_{rms} \times I_{rms} \cos 0$$

$$\left[ P_{av} = V_{rms} \times I_{rms} \right] \text{ (Power loss)}$$

L-ckt

$$\phi = \frac{\pi}{2}$$

$$\cos \phi = \cos \pi/2 = 0$$

[ $P_{av} = 0$ ]  $\rightarrow$  Wattless Current

"The Current which consumes no power for its maintenance in ckt is called Wattless Current"

C-ckt

$$\phi = \pi/2$$

$$\cos \phi = 0$$

[ $P_{av} = 0$ ]  $\rightarrow$  Wattless Current

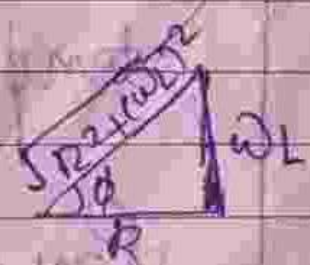
Combination

L-R ckt

$$\tan \phi = \frac{\omega L}{R}$$

$$\cos \phi = \frac{R}{\sqrt{R^2 + (\omega L)^2}}$$

$$P_{av} = V_{rms} \times I_{rms} \times \cos \phi$$



$$P_{av} = V_{rms} \times i_{rms} \times \frac{R}{\sqrt{R^2 + (\omega L)^2}} \quad (\text{Power loss})$$

For C-R ckt

$$\tan \phi = \frac{1}{\omega CR}$$

$$\angle \phi = \phi \text{ not}$$

$$\cos \phi = \frac{\omega CR}{\sqrt{1 + (\omega CR)^2}}$$

$$P_{av} = V_{rms} \times I_{rms} \times \frac{\omega CR}{\sqrt{1 + (\omega CR)^2}}$$

In L-C Ckt

$$\tan \phi = \frac{X_L}{X_C}$$
$$L = \frac{\pi}{2}$$

$$\cos \phi = 0$$

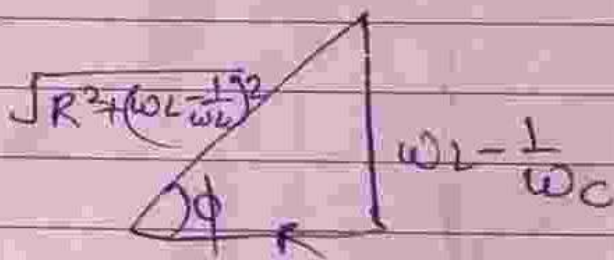
$$P_{av} = I_{rms} \times V_{rms} \times \cos \phi$$

$$[P_{av} = 0]$$

[Wattless Current]

In L-C-R Ckt

$$\tan \phi = \frac{\omega L - \frac{1}{\omega C}}{R}$$



$$P_{av} = V_{rms} \times I_{rms}$$

$$\cos \phi = \frac{R}{\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}}$$

$$[P_{av} = V_{rms} \times I_{rms} \times \frac{R}{\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}}]$$

# ★ TRANSFORMER

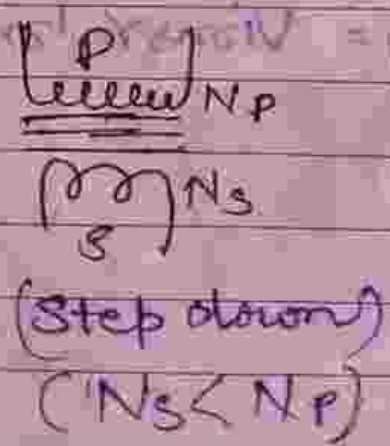
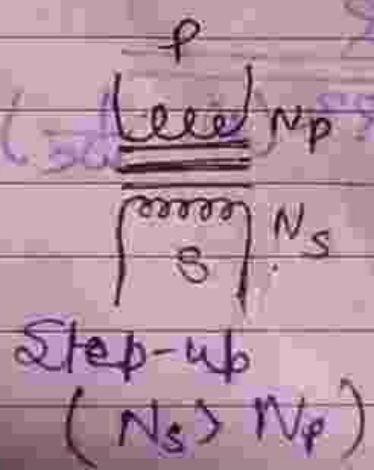
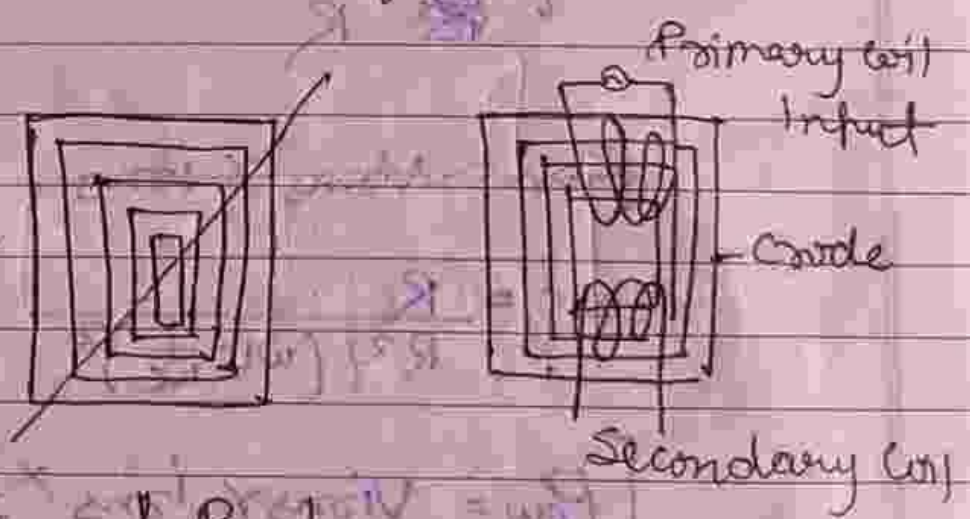
- It is a device which increase or decreased A.C voltage.

- Kind of Transformer

- i) Step-up Transformer
- ii) Step-down "

- Principle → Transformer is based upon mutual inductance

- Construction → It consist two coil primary coil (P) and secondary coil (S) wound and separated on a soft iron core.



## Ideal transformer

A transformer which the primary coil has negligible resistance and all the flux in the core links both primary and secondary coil.

### Working and Theory

Let the No. of turns in primary coil is  $N_p$  and of secondary coil is  $N_s$

then the induced e.m.f. in primary coil

$$e_p = -N_p \frac{d\phi}{dt} \quad \text{--- (1)}$$

and induced e.m.f. in secondary coil

$$e_s = -N_s \frac{d\phi}{dt} \quad \text{--- (2)}$$

$$\text{(2) } \div \text{(1)}$$

$$\left[ \frac{e_s}{e_p} = \frac{N_s}{N_p} \right]$$

If the voltage across primary coil is  $V_p$  and on secondary coil is  $V_s$   
then-

$$\left[ \frac{E_s}{E_p} = \frac{V_s}{V_p} = \frac{N_s}{N_p} = \alpha \right]$$

where  $\alpha$  is Transformer Ratio

i) if  $\alpha > 1$  Step-up Transformer

ii) if  $\alpha < 1$  Step down Transformer.

<p>★ Why <math>N_s &gt; N_p</math> for step up Trans</p> <p><math>\frac{N_s}{N_p} &gt; 1</math></p> <p><math>N_s &gt; N_p</math></p>	<p>For step down</p> <p><math>\frac{N_s}{N_p} &lt; 1</math></p> <p><math>N_p &gt; N_s</math></p>
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# Energy Losses in a Transformer

*There are some energy losses in a transformer*

- (i) **Eddy Current Loss** Eddy current in iron core of transformer facilitate the loss of energy in the form of heat.
- (ii) **Flux Leakage** Total fluxes linked with primary do not completely pass through the secondary which denotes the loss in the flux or flux leakage.
- (iii) **Copper Loss** Due to heating, energy loss takes place in copper wires of primary and secondary coils.
- (iv) **Hysteresis Loss** The energy loss takes place in magnetising and demagnetising the iron core over every cycle.
- (v) **Humming Loss** The magnetostriction effect leads to set the core in vibration which in turn produced the sound. This loss is referred as humming loss.

# Efficiency of transformer

The ratio of output power and input power is called efficiency of transformer.

It is denoted by -  $\eta$

$$\left[ \eta = \frac{\text{output power}}{\text{input power}} \right]$$

If the efficiency of transformer is 100% then power at primary coil will be equal to the power at secondary coil.

Power at primary coil = Power at secondary coil

$$V_p \times I_p = V_s \times I_s$$

$$\left[ \frac{V_s}{V_p} = \frac{I_p}{I_s} \right]$$

So,

$$\left[ \frac{I_s}{I_p} = \frac{V_s}{V_p} = \frac{N_s}{N_p} = \frac{I_p}{I_s} = 0 \right]$$

## ✓ Choke Coil

It is based upon self induction

↓

It is used in A.C. ckt to control current without loss of power.

$$P = V_{rms} \times I_{rms} \cos \phi$$

i. For Resistance

$$\phi = 0$$

$$[P_{rms} = V_{rms} \times I_{rms}]$$

(Powerless) Therefore we can't use Resistance

ii. In Inductance  $\theta = 90^\circ$

$$P = V_{rms} \times I_{rms} \cos 90^\circ$$

$$[P = 0]$$

[Resistor - D.C.  
choke coil - A.C.]